## BI

## Solutions:

Examination date:
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Mock exam

## GRA 60353 Mathematics

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## Question 1.

(a) The partial derivatives of $f(x, y, z, w)=x^{2}-y^{2}+y^{3}+y z+z^{2}+w^{2}$ are given by

$$
f_{x}^{\prime}=2 x, \quad f_{y}^{\prime}=-2 y+3 y^{2}+z, \quad f_{z}^{\prime}=y+2 z, \quad f_{w}^{\prime}=2 w
$$

and its Hessian matrix is given by

$$
H(f)(x, y, z, w)=\left(\begin{array}{cccc}
2 & 0 & 0 & 0 \\
0 & 6 y-2 & 1 & 0 \\
0 & 1 & 2 & 0 \\
0 & 0 & 0 & 2
\end{array}\right)
$$

(b) The stationary points of $f$ are given by

$$
f_{x}^{\prime}=2 x=0, \quad f_{y}^{\prime}=-2 y+3 y^{2}+z=0, \quad f_{z}^{\prime}=y+2 z=0, \quad f_{w}^{\prime}=2 w=0
$$

This gives $x=w=0, y=-2 z$ and $-2 y+3 y^{2}+z=4 z+12 z^{2}+z=0$. The last equation is $5 z+12 z^{2}=z(5+12 z)=0$, with solutions $z=0$ and $z=-5 / 12$. This gives two stationary points $(x, y, z, w)=(0,0,0,0)$ and $(x, y, z, w)=(0,10 / 12,-5 / 12,0)$. The Hessian matrix at $(0,0,0,0)$ has $D_{1}=2$ and $D_{2}=-4$, so this matrix is indefinite. The Hessian matrix at $(0,10 / 12,-5 / 12,0)$ has $D_{1}=2, D_{2}=2 \cdot 3=6, D_{3}=2 \cdot(2(6 y-2)-1)=2 \cdot 5=10$, and $D_{4}=2 D_{3}=20$, so this matrix is positive definite. It follows that $(0,0,0,0)$ is a saddle point and that $(0,10 / 12,-5 / 12,0)$ is a local minimum point.
(c) If the function $f$ was convex or concave, the Hessian matrix $H(f)(x, y, z, w)$ would be either positive semidefinite at all points $(x, y, z, w)$, or negative semidefinite at all points $(x, y, z, w)$. This is not the case, since the Hessian is indefinite at $(0,0,0,0)$. It follows that $f$ is not convex and not concave.

## Question 2.

(a) We compute the determinant of $A$ by cofactor expansion along the first column:

$$
\operatorname{det}(A)=\left|\begin{array}{cccc}
a & 1 & 0 & 0 \\
1 & a & 0 & 0 \\
0 & 0 & 1 & -1 \\
0 & 0 & -1 & 1
\end{array}\right|=a\left(a \cdot\left|\begin{array}{cc}
1 & -1 \\
-1 & 1
\end{array}\right|\right)-1\left(1 \cdot\left|\begin{array}{cc}
1 & -1 \\
-1 & 1
\end{array}\right|\right)=\left(a^{2}-1\right) \cdot\left|\begin{array}{cc}
1 & -1 \\
-1 & 1
\end{array}\right|=0
$$

We therefore have $\operatorname{rk}(A) \leq 3$ for all $a$. To find the $\operatorname{rank}$ of $A$, we use row operations to obtain an echelon form (and start by interchanging the first two rows):

$$
\left(\begin{array}{cccc}
a & 1 & 0 & 0 \\
1 & a & 0 & 0 \\
0 & 0 & 1 & -1 \\
0 & 0 & -1 & 1
\end{array}\right) \Rightarrow\left(\begin{array}{cccc}
1 & a & 0 & 0 \\
0 & 1-a^{2} & 0 & 0 \\
0 & 0 & 1 & -1 \\
0 & 0 & 0 & 0
\end{array}\right)
$$

Since there are two pivot positions when $a^{2}=1$ and three otherwise, we have that

$$
\operatorname{rk}(A)= \begin{cases}3, & a \neq \pm 1 \\ 2, & a= \pm 1\end{cases}
$$

(b) The symmetric matrix $A$ has leading principal minors $D_{i}$ given by

$$
D_{1}=a, \quad D_{2}=a^{2}-1, \quad D_{3}=a^{2}-1, \quad D_{4}=|A|=0
$$

Since $D_{4}=0$, it is necessary to compute all principal minor to find out when $A$ is positive semidefinite, and we find the following principal minors:

$$
\begin{aligned}
\Delta_{1} & =a, a, 1,1 \\
\Delta_{2} & =a^{2}-1, a, a, a, a, 0 \\
\Delta_{3} & =a^{2}-1, a^{2}-1,0,0 \\
\Delta_{4} & =0
\end{aligned}
$$

All principal minors $\Delta_{i} \geq 0$ when $a \geq 0$ and $a^{2}-1 \geq 0$, so $A$ is positive semidefinite for $a \geq 1$ (and indefinite when $a<1$ ).
(c) The characteristic polynomial of $A$ (the left side of the characteristic equation) is given by

$$
\left|\begin{array}{cccc}
a-\lambda & 1 & 0 & 0 \\
1 & a-\lambda & 0 & 0 \\
0 & 0 & 1-\lambda & -1 \\
0 & 0 & -1 & 1-\lambda
\end{array}\right|=(a-\lambda)\left((a-\lambda) \cdot\left|\begin{array}{cc}
1-\lambda & -1 \\
-1 & 1-\lambda
\end{array}\right|\right)-1\left(1 \cdot\left|\begin{array}{cc}
1-\lambda & -1 \\
-1 & 1-\lambda
\end{array}\right|\right)
$$

Hence the characteristic equation is given by

$$
\left((a-\lambda)^{2}-1\right)\left|\begin{array}{cc}
1-\lambda & -1 \\
-1 & 1-\lambda
\end{array}\right|=\left((a-\lambda)^{2}-1\right)\left(\lambda^{2}-2 \lambda\right)=0
$$

which can be expressed as $(a-\lambda)^{2}-1=0$ or $\lambda^{2}-2 \lambda=0$. The eigenvalues are therefore $\lambda=a+1, \lambda=a-1, \lambda=0$ and $\lambda=2$.

## Question 3.

(a) The differential equation $y^{\prime \prime}-7 y^{\prime}+10 y=4 e^{t}-5$ is second order linear, and it has solution $y=y_{h}+y_{p}$. The homogeneous equation $y^{\prime \prime}-7 y^{\prime}+10 y=0$ has characteristic equation $r^{2}-7 r+10=0$, and distinct roots $r=2$ and $r=5$. Therefore $y_{h}=C_{1} e^{2 t}+C_{2} e^{5 t}$. To find a particular solution $y_{p}$, we consider the right hand side $f(t)=4 e^{t}-5$ and its derivatives $f^{\prime}=4 e^{t}$ and $f^{\prime \prime}=4 e^{t}$. We guess that there is a solution of the form $y=A e^{t}+B$. Inserting this guess in the differential equation, we obtain

$$
A e^{t}-7\left(A e^{t}\right)+10\left(A e^{t}+B\right)=4 e^{t}-5
$$

or $4 A e^{t}+10 B=4 e^{t}-5$. We see that $A=1$ and $B=-1 / 2$ is a solution, so $y_{p}=e^{t}-1 / 2$ and the general solution is

$$
y=y_{h}+y_{p}=C_{1} e^{2 t}+C_{2} e^{5 t}+e^{t}-1 / 2
$$

(b) The differential equation $t y^{\prime}+(2-t) y=e^{2 t}$ is first order linear since it can be written in standard form as

$$
y^{\prime}+\frac{2-t}{t} y=t^{-1} e^{2 t}
$$

It can be solved using integrating factor, and

$$
\int \frac{2-t}{t} d t=\int(2 / t-1) d t=2 \ln t-t+\mathcal{C}
$$

so the integrating factor is $u=e^{2 \ln t-t}=t^{2} e^{-t}$. After multiplying with the integrating factor, we get

$$
(y u)^{\prime}=t^{-1} e^{2 t} u=t e^{t} \quad \Rightarrow \quad y=\frac{1}{u} \int t e^{t} d t=\frac{t e^{t}-e^{t}+\mathcal{C}}{t^{2} e^{-t}}=\frac{t-1}{t^{2}} e^{2 t}+\frac{\mathcal{C}}{t^{2}} e^{t}
$$

(c) The differential equation $3 y^{2} t e^{-t} y^{\prime}+\left(y^{3}-1\right) e^{-t}=t e^{-t} y^{3}$ can be written as $p y^{\prime}+q=0$ with

$$
p=3 y^{2} t e^{-t}, \quad q=\left(y^{3}-1\right) e^{-t}-t e^{-t} y^{3}
$$

We try to find a function $h=h(y, t)$ such that $h_{y}^{\prime}=p$ and $h_{t}^{\prime}=q$. From the first condition, we get

$$
h=y^{3} t e^{-t}+\phi(t)
$$

and using this expression for $h$, the second condition becomes $h_{t}^{\prime}=q$, where

$$
\begin{aligned}
h_{t}^{\prime}=y^{3}\left(1 \cdot e^{-t}+t e^{-t}(-1)\right)+\phi^{\prime}(t) & =y^{3} e^{-t}-y^{3} t e^{-t}+\phi^{\prime}(t) \\
q=\left(y^{3}-1\right) e^{-t}-t e^{-t} y^{3} & =y^{3} e^{-t}-e^{-t}-y^{3} t e^{-t}
\end{aligned}
$$

Hence $h_{t}^{\prime}=q$ holds if $\phi^{\prime}(t)=-e^{-t}$. We may therefore choose $\phi(t)=e^{-t}$, and we find a function $h=y^{3} t e^{-t}+e^{-t}$ that satisfies $h_{y}^{\prime}=p$ and $h_{t}^{\prime}=q$. This means that the differential equation is exact, with solution

$$
h=y^{3} t e^{-t}+e^{-t}=\mathcal{C} \quad \Rightarrow \quad y=\sqrt[3]{\frac{\mathcal{C} e^{t}-1}{t}}
$$

## Question 4.

(a) We write the Kuhn-Tucker problem in standard form as

$$
\max -f(x, y, z, w)=-x^{2}-y^{2}-z^{2}-w^{2} \text { subject to }\left\{\begin{array}{l}
x y+1 \leq 0 \\
2 z w+8 \leq 0
\end{array}\right.
$$

and we form the Lagrangian

$$
\mathcal{L}=-x^{2}-y^{2}-z^{2}-w^{2}-\lambda_{1}(x y+1)-\lambda_{2}(2 z w+8)
$$

The first order conditions (FOC) are

$$
\begin{aligned}
\mathcal{L}_{x}^{\prime} & =-2 x-\lambda_{1} y=0 \\
\mathcal{L}_{y}^{\prime} & =-2 y-\lambda_{1} x=0 \\
\mathcal{L}_{z}^{\prime} & =-2 z-\lambda_{2} \cdot 2 w=0 \\
\mathcal{L}_{w}^{\prime} & =-2 w-\lambda_{2} \cdot 2 z=0
\end{aligned}
$$

the constraints (C) are given by $x y+1 \leq 0$ and $2 z w+8 \leq 0$, and the complementary slackness conditions (CSC) are given by

$$
\begin{array}{ll}
\lambda_{1} \geq 0 & \text { and } \lambda_{1}(x y+1)=0 \\
\lambda_{2} \geq 0 & \text { and } \lambda_{2}(2 z w+8)=0
\end{array}
$$

When $(x, y, z, w)=(1,-1,2,-2)$, the FOC's give $-2+\lambda_{1}=0$ and $-4+4 \lambda_{2}=0$, or $\lambda_{1}=2$ and $\lambda_{2}=1$. Since $x y=-1$ and $z w=-4$, the C's are satisfied and binding, and the CSC's are satisfied. So $\left(x, y, z, w ; \lambda_{1}, \lambda_{2}\right)=(1,-1,2,-2 ; 2,1)$ is a solution of the K-T conditions.
(b) We prove that $(x, y, z, w)=(1,-1,2,-2)$ is max for $-f$ (and a min for $f$ ) using the SOC: If $h(x, y, z, w)=\mathcal{L}(x, y, z, w ; 2,1)=-x^{2}-y^{2}-z^{2}-w^{2}-2(x y+1)-(2 z w+8)$ is a concave funtion in $(x, y, z, w)$, then $(x, y, z, w)=(1,-1,2,-2)$ is a maximum point for $-f$. The Hessian matrix of $h$ is

$$
H(h)=\left(\begin{array}{cccc}
-2 & -2 & 0 & 0 \\
-2 & -2 & 0 & 0 \\
0 & 0 & -2 & -2 \\
0 & 0 & -2 & -2
\end{array}\right)
$$

This is a symmetric matrix with leading principal minors $D_{1}=-2, D_{2}=0, D_{3}=0$ and $D_{4}=0$. We compute the principal minors of order one and two:

$$
\begin{aligned}
& \Delta_{1}=-2,-2,-2,-2 \\
& \Delta_{2}=0,4,4,4,4,0
\end{aligned}
$$

The Hessian matrix is clearly of rank two, so all principal minors of order three and four are zero. This implies that $h$ is a concave function, and therefore $(x, y, z, w)=(1,-1,2,-2)$ solves the KT problem. The minimum value of $f$ is $f(1,-1,2,-2)=1+1+4+4=10$.
(c) Let us consider the KT problem

$$
\max -f(x, y, z, w)=-x^{2}-y^{2}-z^{2}-w^{2} \text { subject to }\left\{\begin{array}{l}
x y+1 \leq 0 \\
2 z w+c \leq 0
\end{array}\right.
$$

with Lagrangian $\mathcal{L}=-x^{2}-y^{2}-z^{2}-w^{2}-\lambda_{1}(x y+1)-\lambda_{2}(2 z w+c)$. When $c=8$, we have found the maximum value $-f=-(1+1+4+4)=-10$. When we change $c$ to $c=7.9$, it follows from the Envelope theorem that the change in maximum value is estimated by

$$
\Delta c \cdot \mathcal{L}_{c}^{\prime}\left(x^{*}(c), y^{*}(c), z^{*}(c), w^{*}(c) ; \lambda_{1}^{*}(c), \lambda_{2}^{*}(c)\right)=-0.1 \cdot\left(-\lambda_{2}^{*}(8)\right)=0.1
$$

since $\lambda_{2}^{*}(8)=1$. The new maximal value for $-f$ is approximately $-10+0.1=-9.9$, and the new minimum value for $f$ is approximately $f=9.9$.
(d) Consider the first order conditions (FOC) given by

$$
\begin{aligned}
\mathcal{L}_{x}^{\prime} & =-2 x-\lambda_{1} y=0 \\
\mathcal{L}_{y}^{\prime} & =-2 y-\lambda_{1} x=0 \\
\mathcal{L}_{z}^{\prime} & =-2 z-\lambda_{2} 2 w=0 \\
\mathcal{L}_{w}^{\prime} & =-2 w-\lambda_{2} 2 z=0
\end{aligned}
$$

If $\lambda_{1}=0$, then $x=y=0$, and this does not satisfy the first constraint. If $\lambda_{2}=0$, then $z=w=0$, and this does not satisfy the second constraint. Therefore $\lambda_{1}, \lambda_{2}>0$, and $x y=-1$ and $z w=-4$ by the CSC's. In particular, $x, y, z, w \neq 0$. The first two conditions give $y=-2 x / \lambda_{1}$ and $x=-2 y / \lambda_{1}$. When we combine these condtions, we get

$$
x=-2 y / \lambda_{1}=\left(2 / \lambda_{1}\right)^{2} x \quad \Rightarrow \quad \lambda_{1}=2
$$

since $x \neq 0$. This implies that $x=-y$ and since $x y=-1$, we must have $x^{2}=1$. We get two solutions $(x, y)=(1,-1)$ or $(x, y)=(-1,1)$ with $\lambda_{1}=2$. The last two FOC's give $w=-z / \lambda_{2}$ and $z=-w / \lambda_{2}$. When we combine these condtions, we get

$$
z=-w / \lambda_{2}=\left(1 / \lambda_{1}\right)^{2} z \quad \Rightarrow \quad \lambda_{2}=1
$$

since $z \neq 0$. This implies that $z=-w$ and since $z w=-4$, we must have $z^{2}=4$. We get two solutions $(z, w)=(2,-2)$ or $(x, y)=(-2,2)$ with $\lambda_{2}=1$. All four candidates satisfy $\mathrm{C}+$ CSC as well as FOC, so the points

$$
\begin{aligned}
& \left(x, y, z, w ; \lambda_{1}, \lambda_{2}\right)=(1,-1,2,-2 ; 2,1) \\
& \left(x, y, z, w ; \lambda_{1}, \lambda_{2}\right)=(-1,1,2,-2 ; 2,1) \\
& \left(x, y, z, w ; \lambda_{1}, \lambda_{2}\right)=(1,-1,-2,2 ; 2,1) \\
& \left(x, y, z, w ; \lambda_{1}, \lambda_{2}\right)=(-1,1,-2,2 ; 2,1)
\end{aligned}
$$

are the solutions of the KT conditions.

