

LECTURE 1

GKA 6035

EIVIND EIKSEN, AUG 26TH 2011

- Lecture plan:
- ① Intro to GKA 6035
 - ② Linear Systems
 - ③ Gaussian elimination
 - ④ Rank of a matrix

Notes:

[L6E] Ch. 1-3
(+ [FMEA] Ch. 1.3-1.4)

① Intro to GKA 6035

- Lectures
- Problem Sessions
- Exam →

Midterm 30/09
Final ~~12/12~~ 12/12
(~~temporary date~~)
(~~not finalized~~)

- Reading
- Prerequisites

See syllabus /
It's Learning

② Linear Systems

A linear equation in x_1, x_2, \dots, x_n (variables) is of the form

$$a_1 x_1 + a_2 x_2 + \dots + a_n x_n = b$$

where a_1, \dots, a_n and b are fixed numbers (parameters).

Ex:

$$x_1 + x_2 = 7$$
$$x + 2y - z = 13$$

Linear equations have graphs that are straight lines (two vars) / planes (three vars).

A linear system in x_1, x_2, \dots, x_n (variables) is a collection of one or more linear equations in these variables.

In general: $m \times n$ linear system

$$\left. \begin{array}{l} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{array} \right\} \begin{array}{l} m \\ \text{equations} \end{array}$$

$\underbrace{\hspace{15em}}_{n \text{ variables}}$

Ex:
$$\begin{array}{l} x + y = 4 \\ x - y = 2 \end{array} \quad (2 \times 2 \text{ lin. system})$$

A solution of a linear system in x_1, x_2, \dots, x_n is an n -tuple (s_1, s_2, \dots, s_n) such that

$$x_1 = s_1, x_2 = s_2, \dots, x_n = s_n$$

solve all equations simultaneously.

Ex: $x+y=4$
 $x-y=2$

Substitution

$$x+y=4 \Rightarrow y=4-x$$

$$x-y=2$$

$$x-(4-x)=2$$

$$2x-4=2$$

$$x=3$$

$$\rightarrow y=4-3=1$$

$$(x,y) = \underline{\underline{(3,1)}}$$

Elimination

$$x+y=4$$

$$x-y=2$$

$$\hline 2x = 6$$

$$x=3$$

← $\left. \begin{array}{l} \text{var. } y \\ \text{is} \\ \text{eliminated} \end{array} \right\}$

$$\rightarrow x+y=4$$

$$y=4-x$$

$$=4-3=1$$

$$x+y=4$$

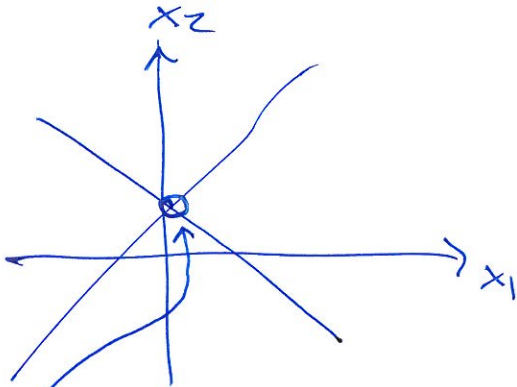
$$x-y=2$$

$$\rightarrow \left(\begin{array}{l} x+y=4 \\ 2x=6 \end{array} \right)$$

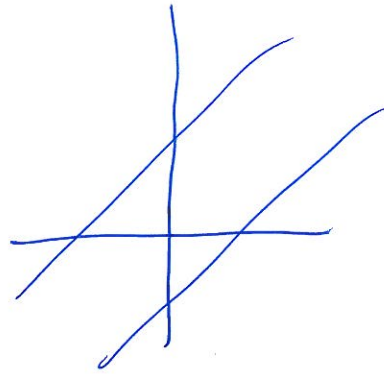
Solution types:

Ex: 2×2 system

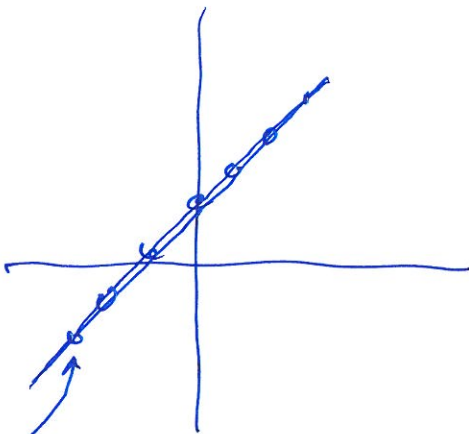
$$\begin{cases} a_{11}x_1 + a_{12}x_2 = b_1 \\ a_{21}x_1 + a_{22}x_2 = b_2 \end{cases}$$



non-parallel lines
one solution



parallel lines, but different
no solutions



parallel lines, the same
infinitely many solutions
(all points on the line)

Theorem:

Any linear system ($m \times n$)

has either

- one solution
- no solutions
- infinitely many solutions

② Gaussian elimination

— Operate on systems not equations

$$\begin{array}{l} x+y=4 \\ x-y=2 \end{array} \rightarrow \begin{array}{l} x+y=4 \\ 2x=6 \end{array}$$

It is useful to have a shorter notation.

A matrix is a rectangular array of numbers.

The coefficient matrix of a linear system

$$A = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \leftarrow \begin{array}{l} x+y=4 \\ x-y=2 \end{array}$$

The augmented matrix

$$\hat{A} = \left(\begin{array}{cc|c} 1 & 1 & 4 \\ 1 & -1 & 2 \end{array} \right) \leftarrow \begin{array}{l} x+y=4 \\ x-y=2 \end{array}$$

Notation:

$$\left(\begin{array}{cc|c} 1 & 1 & 4 \\ 1 & -1 & 2 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & 1 & 4 \\ 2 & 0 & 6 \end{array} \right)$$

means

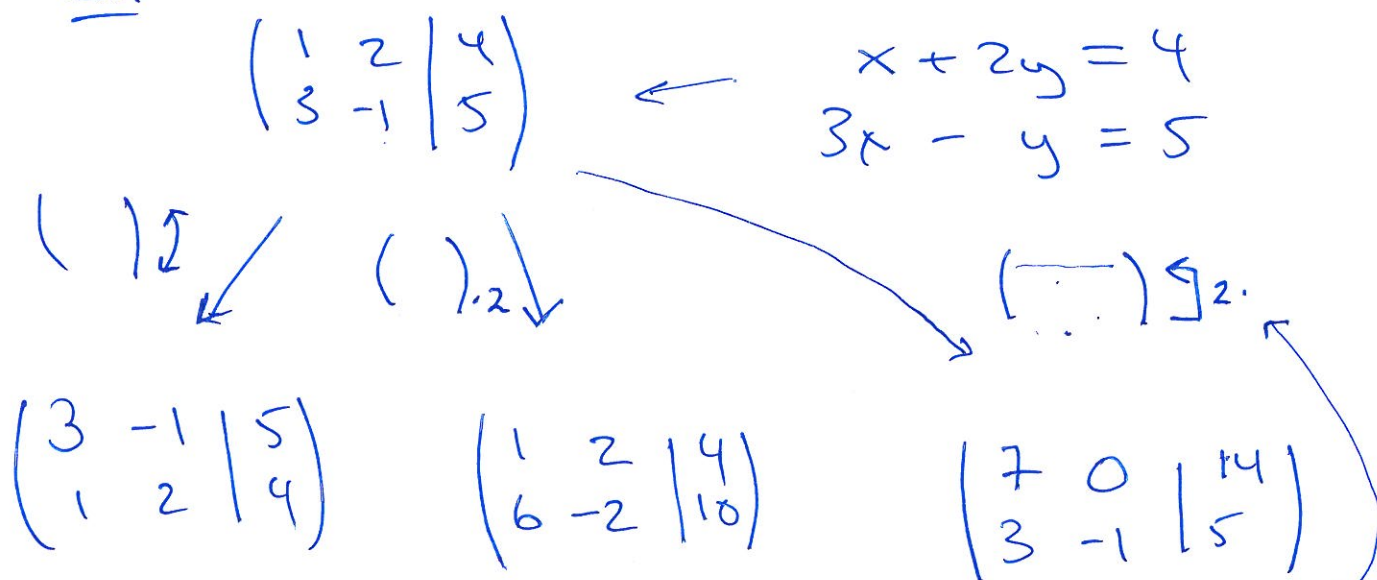
$$\begin{array}{l} x+y=4 \\ x-y=2 \end{array} \rightarrow \begin{array}{l} x+y=4 \\ 2x=6 \end{array}$$

- Allowed operations = Operations that preserve the solutions of the system

Row operations = Elementary row operation

- ① Interchange two rows
- ② Multiply a row with a non-zero constant number
- ③ Change a row by adding to it a multiple of another row

Ex:



Many other notations are possible, such as:

$$\begin{cases} \text{Row 1} := \text{Row 1} + 2 \text{Row 2} \\ \text{Row 2} = \text{unchanged} \end{cases}$$

Fact:

- Row operations are allowed (preserve solutions)
- All linear systems can be solved using elementary row operations.

Target: to eliminate as many variables as possible using elementary row op.

Ex. 1:

$$\begin{aligned} x + y &= 4 \\ x - y &= 2 \end{aligned}$$

$$\begin{aligned} x + y &= 4 \\ -2y &= -2 \end{aligned}$$

↑

$$\left(\begin{array}{cc|c} \textcircled{1} & 1 & 4 \\ & -1 & 2 \end{array} \right) \xrightarrow{-1} \left(\begin{array}{cc|c} \textcircled{1} & 1 & 4 \\ 0 & \textcircled{-2} & -2 \end{array} \right)$$

↑
want to get 0 in this position

Row operation:

$$R_1 \leftarrow R_1$$

$$R_2 \leftarrow R_2 + (-1) \cdot R_1$$

Back substitution:

$$\begin{aligned} -2y &= -2 & x + y &= 4 \\ y &= \underline{1} & x &= \underline{3} \end{aligned}$$

Ex. 2:

$$\begin{aligned} S + 0.05C &= 5,000 \\ 0.4S + F + 0.4C &= 40,000 \\ 0.1S + 0.1F + C &= 10,000 \end{aligned}$$

$$\left(\begin{array}{ccc|c} \textcircled{1} & 0 & 0.05 & 5,000 \\ 0.4 & 1 & 0.4 & 40,000 \\ 0.1 & 0.1 & 1 & 10,000 \end{array} \right) \xrightarrow{-0.4} \left(\begin{array}{ccc|c} \textcircled{1} & 0 & 0.05 & 5,000 \\ 0 & \textcircled{1} & 0.38 & 38,000 \\ 0 & 0.1 & 0.995 & 9,500 \end{array} \right)$$

eliminate S from }
eq. (2) and (3)

eliminate F }
from eq. (3)

$$\rightarrow \left(\begin{array}{cc|c} \textcircled{1} & 0 & 5,000 \\ 0 & \textcircled{1} & 38,000 \\ 0 & 0 & \textcircled{0.957} \end{array} \right)$$

← { we cannot eliminate any more vars

This means:

$$\begin{aligned} S + 0.05C &= 5,000 \\ F + 0.38C &= 38,000 \\ 0.957C &= 5,700 \Rightarrow C = \underline{5,956} \\ F &= 38,000 - 0.38 \cdot (5,956) = \underline{35,737} \\ S &= 5,000 - 0.05 \cdot (5,956) = \underline{4,702} \end{aligned}$$

Solution:

~~$$\begin{aligned} S &= 4,702 \\ F &= 35,737 \\ C &= 4, \end{aligned}$$~~

$$\begin{aligned} S &= 4,702 \\ F &= 35,737 \\ C &= \underline{\underline{5,956}} \end{aligned}$$

(rounded to the nearest dollar)

Echelon forms:

Pivot = the first non-zero number in a row in the matrix.

Echelon form = all entries under a pivot are zero

$$\begin{pmatrix} 7 & 2 & 3 \\ 0 & 5 & 1 \\ 0 & 0 & 0 \end{pmatrix} \text{ echelon form}$$

Augmented matrix in echelon form

→

Stop the row operations.

Gaussian elimination:

lin. sys.

→

augmented matrix

↓

row operations

echelon form

←

lin. sys.
w/ variables eliminated

↓

back substitution

↓

solution

Variation: Gauss-Jordan elimination

A reduced echelon form is a matrix such that

* all entries under a pivot are zero

* $\begin{array}{c} | \\ | \\ \hline | \\ | \end{array}$ over $\begin{array}{c} | \\ | \\ \hline | \\ | \end{array}$

* all pivots are 1

Ex:

$$\left(\begin{array}{cc|c} 3 & 7 & 4 \\ 0 & 2 & 1 \end{array} \right)$$

echelon form

but not reduced echelon form

↓

$$\left(\begin{array}{cc|c} 1 & 0 & 0.17 \\ 0 & 1 & 0.5 \end{array} \right)$$

reduced echelon form

When we continue with row operations until we get a reduced echelon form, the method is called Gauss-Jordan elimination.

Facts:

- When we use row operations on a given matrix, an echelon form is not unique, but the reduced echelon form is unique

- Pivot positions = $\left\{ \begin{array}{l} \text{positions where there are} \\ \text{pivots in an echelon} \\ \text{form (after row operations)} \end{array} \right.$

The pivot positions are unique; that is, all echelon forms we get to from a given matrix has the same pivot positions

Systems with no solutions:

Ex:

$$\left(\begin{array}{ccc|c} \textcircled{1} & 2 & 3 & 5 \\ 0 & 0 & \textcircled{7} & 4 \\ 0 & 0 & 0 & \textcircled{3} \end{array} \right)$$

echelon form

$$x + 2y + 3z = 5$$

$$7z = 4$$

$$0 = 3$$

↑
no solutions

A linear system has no solutions (inconsistent)



= pivot position in last column.

An echelon form has a pivot in the last column.

A pivot position is a position in the matrix where there is a pivot when the matrix is reduced to an echelon form.

$$\left(\begin{array}{ccc|c} \textcircled{1} & 2 & 3 & 5 \\ 0 & 0 & \textcircled{7} & 4 \\ \textcircled{1} & 2 & 10 & 12 \end{array} \right)$$

→ ... →

$$\left(\begin{array}{ccc|c} \textcircled{1} & 2 & 3 & 5 \\ 0 & 0 & \textcircled{7} & 4 \\ 0 & 0 & 0 & \textcircled{3} \end{array} \right)$$

Systems with many solutions

Ex:
$$\left(\begin{array}{ccc|c} \textcircled{1} & 2 & 3 & 1 \\ 0 & \textcircled{-4} & -8 & -2 \end{array} \right) \text{ echelon form}$$

x y z

no pivots position in last col. \Rightarrow there are solutions (consistent)

Look at pivot positions:

Each column on the left side of the line = one variable

Basic variable = columns with pivot positions

Free variable = " without —|—

Ex: x, y basic, z free

We can solve each basic variable in terms of the free ones:

$$\textcircled{x} + 2y + 3z = 1$$

$$\textcircled{-4y} - 8z = -2 \Rightarrow -4y = 8z - 2$$

$$y = -2z + \frac{1}{2}$$

Back substitution:

We work backwards

$$x + 2\left(-2z + \frac{1}{2}\right) + 3z = 1$$

$$x = \underline{z}$$

$$x = z$$

$$y = -2z + \frac{1}{2}$$

$$z = \text{free}$$

Summary:

(a) $\left\{ \begin{array}{l} \text{System is consistent} \iff \text{no pivot position} \\ \text{(at least one sol'n.)} \quad \text{in the last col.} \\ \\ \text{System is inconsistent} \iff \text{pivot position} \\ \text{(no sol'n.)} \quad \text{in the last column.} \end{array} \right.$

b) Assume that the system is consistent

all variables are basic (one solution) \iff pivot positions in all columns to the left of the line

Some variables are free (infinitely many sol'n.) \iff at least one column to the left of the line without a pivot position.

degrees of freedom
 $= \#$ free variables

④ Rank

The rank of a matrix is the number of pivot positions

$$\text{rk } A = \# \text{ pivot positions in } A$$

A $m \times n$ -matrix: $\text{rk } A \leq m, \text{rk } A \leq n$
 $\text{rk } A = 0 \iff$ all entries in A are zero

Ex:

$$\begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & 1 \\ 2 & 4 & 7 \end{pmatrix} \rightarrow \begin{pmatrix} \textcircled{1} & 2 & 3 \\ 0 & \textcircled{-3} & -2 \\ 0 & 0 & \textcircled{1} \end{pmatrix}$$

↑ row operations

↑ three pivot positions

$$\text{rk} \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & 1 \\ 2 & 4 & 7 \end{pmatrix} = \underline{\underline{3}}$$

Next Lecture: Thursday 01/09 at 17.00 in C1-010

- More details for this lecture: See "Linear Systems and Gaussian Elimination" (notes in It's Learning)
- Work through exercises from Problem Sheet 1.