

Solutions:	GRA 60353 Mathematics
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Permitted examination aids:	Bilingual dictionary BI-approved exam calculator: TEXAS INSTRUMENTS BA II Plus TM
Answer sheets:	Squares
Total number of pages:	4

QUESTION 1.

(a) We compute the partial derivatives $f'_x = (x^2 + 2x)e^x$, $f'_y = z$ and $f'_z = y - 3z^2$. The stationary points are given by the equations

$$(x^{2}+2x)e^{x} = 0, \quad z = 0, \quad y - 3z^{2} = 0$$

and this gives x = 0 or x = -2 from the first equation and y = 0 and z = 0 from the last two. The stationary points are therefore (x, y, z) = (0, 0, 0), (-2, 0, 0).

(b) We compute the second order partial derivatives of f and form the Hessian matrix

$$f'' = \begin{pmatrix} (x^2 + 4x + 2)e^x & 0 & 0\\ 0 & 0 & 1\\ 0 & 1 & -6z \end{pmatrix}$$

We see that the second order principal minor obtained from the last two rows and columns is

$$\begin{vmatrix} 0 & 1 \\ 1 & -6z \end{vmatrix} = -1 < 0$$

hence the Hessian is indefinite in all stationary points. Therefore, both stationary points are saddle points.

(a) The determinant of A is given by

$$\det(A) = \begin{vmatrix} 1 & 7 & -2 \\ 0 & s & 0 \\ 1 & 1 & 4 \end{vmatrix} = s(4+2) = \boxed{6s}$$

It follows that the rank of A is 3 if $s \neq 0$ (since det $(A) \neq 0$). When s = 0, A has rank 2 since det(A) = 0 but the minor

$$\begin{vmatrix} 1 & -2 \\ 1 & 4 \end{vmatrix} = 6 \neq 0$$

Therefore, we get

$$\operatorname{rk}(A) = \begin{cases} 3, & s \neq 0\\ 2, & s = 0 \end{cases}$$

(b) We compute the characteristic equation of A, and find that

$$\begin{vmatrix} 1-\lambda & 7 & -2\\ 0 & s-\lambda & 0\\ 1 & 1 & 4-\lambda \end{vmatrix} = (s-\lambda)(\lambda^2 - 5\lambda + 6) = (s-\lambda)(\lambda - 2)(\lambda - 3)$$

Therefore, the eigenvalues of A are $\lambda = s, 2, 3$. Furthermore, we have that

$$A\mathbf{v} = \begin{pmatrix} 6\\s\\6 \end{pmatrix}$$

We see that **v** is an eigenvector for A if and only if s = 6, in which case $A\mathbf{v} = 6\mathbf{v}$.

(c) If $s \neq 2, 3$, then A has three distinct eigenvalues, and therefore A is diagonalizable. If s = 2, we check the eigenspace corresponding to the double root $\lambda = 2$: The coefficient matrix of the system has echelon form

$$\begin{pmatrix} -1 & 7 & -2 \\ 0 & 0 & 0 \\ 1 & 1 & 2 \end{pmatrix} \dashrightarrow \begin{pmatrix} 1 & 1 & 2 \\ 0 & 8 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

of rank two, so there is only one free variable. If s = 3, we check the eigenspace corresponding to the double root $\lambda = 3$: The coefficient matrix of the system has echelon form

$$\begin{pmatrix} -2 & 7 & -2 \\ 0 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix} \dashrightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 9 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

of rank two, so there is only one free variable. In both cases, there are too few linearly independent eigenvectors, and A is not diagonalizable. Hence A is diagonalizable if $|s \neq 2, 3|$

QUESTION 3.

(a) We have $b_{t+1} - b_t = rb_t - s_{t+1}$, where $s_{t+1} = 500 + 10t$ is the repayment in period t+1. Hence we get the difference equation

$$b_{t+1} = (1+r)b_t - (500+10t), \quad b_0 = K$$

The homogenous solution is $b_t^h = C(1+r)^t$. We try to find a particular solution of the form $b_t = At + B$, which gives $b_{t+1} = At + A + B$. Substitution in the difference equation gives

$$At + A + B = (1+r)(At + B) - (500 + 10t) = ((1+r)A - 10)t + (1+r)B - 500$$

and this gives A = 10/r and $B = 10/r^2 + 500/r$. Hence the solution of the difference equation is

$$b_t = b_t^h + b_t^p = C(1+r)^t + \frac{10}{r}t + \frac{10}{r^2} + \frac{500}{r}t$$

The initial value condition is $K = C + 10/r^2 + 500/r$, hence we obtain the solution

$$b_t = \left(K - \frac{10}{r^2} - \frac{500}{r}\right)(1+r)^t + \frac{10}{r}t + \frac{10}{r^2} + \frac{500}{r}$$

(b) The homogeneous equation y'' + y' - 6y = 0 has characteristic equation $r^2 + r - 6 = 0$ and roots r = 2 and r = -3, so $y_h = C_1 e^{2t} + C_2 e^{-3t}$. We try to find a particular solution of the form $y = (At + B)e^t$, which gives

$$y' = (At + A + B)e^t, \quad y'' = (At + 2A + B)e^t$$

Substitution in the differential equation gives

$$(At + 2A + B)e^t + (At + A + B)e^t - 6(At + B)e^t = te^t \Leftrightarrow -4A = 1 \text{ and } 3A - 4B = 0$$

This gives A = -1/4 and B = -3/16. Hence the general solution of the differential equation

is
$$y = y_h + y_p = \boxed{C_1 e^{2t} + C_2 e^{-3t} - (\frac{1}{4}t + \frac{3}{16})e^t}_2$$

(c) The differential equation can be written in the form

$$\left(3t^2 - \frac{1}{y}\right) + \frac{t}{y^2}y' = 0$$

and we see that it is exact. Hence it can be written of the form u(y,t) = C, where u(y,t) is a function that satisfies

$$\frac{\partial u}{\partial t} = 3t^2 - \frac{1}{y}$$
 and $\frac{\partial u}{\partial y} = \frac{t}{y^2}$

One solution is $u(y,t) = t^3 - t/y$, and this gives

$$t^3 - \frac{t}{y} = C \quad \Leftrightarrow \quad y = \frac{t}{t^3 - C}$$

The initial condition gives 1/(1 - C) = 1/3 or C = -2. The solution to the initial value problem is therefore

$$y = \boxed{\frac{t}{t^3 + 2}}$$

QUESTION 4.

(a) We compute the Hessian of g, and find

$$g'' = \frac{1}{xyz} \begin{pmatrix} \frac{2}{x^2} & \frac{1}{xy} & \frac{1}{xz} \\ \frac{1}{xy} & \frac{2}{y^2} & \frac{1}{yz} \\ \frac{1}{xz} & \frac{1}{yz} & \frac{2}{z^2} \end{pmatrix}$$

Hence the leading principal minors are

$$D_1 = \frac{1}{xyz}\frac{2}{x^2} > 0, \quad D_2 = \frac{1}{(xyz)^2}\frac{3}{(xy)^2} > 0, \quad D_3 = \frac{1}{(xyz)^3}\frac{4}{(xyz)^2} > 0$$

This means that g is convex.

(b) The set $\{(x, y, z) : x^2 + y^2 + z^2 \le 1\}$ is closed and bounded, so the problem has solutions by the extreme value theorem. The NDCQ is satisfied, since the rank of $\begin{pmatrix} 2x & 2y & 2z \end{pmatrix} = 1$ when $x^2 + y^2 + z^2 = 1$. We form the Lagrangian

$$\mathcal{L} = xyz - \lambda(x^2 + y^2 + z^2 - 1)$$

and solve the Kuhn-Tucker conditions, consisting of the first order conditions

$$\mathcal{L}'_{x} = yz - \lambda \cdot 2x = 0$$

$$\mathcal{L}'_{y} = xz - \lambda \cdot 2y = 0$$

$$\mathcal{L}'_{z} = xy - \lambda \cdot 2z = 0$$

together with one of the following conditions: i) $x^2 + y^2 + z^2 = 1$ and $\lambda \ge 0$ or ii) $x^2 + y^2 + z^2 < 1$ and $\lambda = 0$. We first solve the equations/inequalities in case i): If x = 0, then we see that y = 0or z = 0 from the first equation, and we get the solutions $(x, y, z; \lambda) = (0, 0, \pm 1; 0), (0, \pm 1, 0; 0)$. If $x \ne 0$, we get $2\lambda = yz/x$ and the remaining first order conditions give $(x^2 - y^2)z = 0$ and $(x^2 - z^2)y = 0$. If y = 0, we get the solution $(\pm 1, 0, 0; 0)$. Otherwise, we get $x^2 = y^2 = z^2$, hence

$$(x, y, z; \lambda) = \left(\pm \frac{1}{\sqrt{3}}, \pm \frac{1}{\sqrt{3}}, \pm \frac{1}{\sqrt{3}}; \pm \frac{1}{2\sqrt{3}}\right)$$

The condition that $\lambda \ge 0$ give that either all three coordinates (x, y, z) are positive, or that one is positive and two are negative. In total, we obtain four different solutions. We note that $f(x, y, z) = \frac{1}{3\sqrt{3}}$ for each of these four solutions, while f(x, y, z) = 0 for either of the first three solutions. Finally, we consider case ii), where $\lambda = 0$. This gives xy = xz = yz = 0, and we obtain

$$(x, y, z; \lambda) = (a, 0, 0; 0), (0, a, 0; 0), (0, 0, a; 0)$$

The condition that $x^2 + y^2 + z^2 < 1$ give $a^2 \le 1$ or $a \in (-1, 1)$. For all these solutions, we get f(x, y, z) = 0. We can therefore conclude that the solution to the optimization problem is a maximum value of

